## **The Moment Problem**

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### Motivation

- 2 What the moment problem is?
- Existence and uniqueness of the solution operator approach
- Jacobi matrix and Orthogonal Polynomials
- Sufficient conditions for determinacy
- The set of solutions of indeterminate moment problem

$$\int_{\mathbb{R}} x^n f(x) dx = \int_{\mathbb{R}} x^n e^{-x^2} dx, \quad n = 0, 1, \dots$$

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- What happens if one replaces the normal density by something else?
- The general answer to the Chebychev's question is *no*. Suppose, e.g., X ~ N(0, σ<sup>2</sup>) and consider densities of exp(X) (lognormal distribution) or sinh(X) then we lost the uniqueness.

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A tough problem: What can be said when there is no longer uniqueness?

$$\int_{I} x^{n} d\mu(x),$$
 (provided the integral exists).

Suppose a real sequence  $\{s_n\}_{n\geq 0}$  is given. The moment problem on *I* consists of solving the following three problems:

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- (a) how one can describe all positive measures on *I* with moments  $\{s_n\}_{n\geq 0}$ ? (*indeterminate case*)

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One can restrict oneself to cases:

- $I = \mathbb{R}$  *Hamburger* moment problem ( $M_H$  = set of solutions)
- $I = [0, +\infty)$  *Stieltjes* moment problem ( $M_S$  = set of solutions)
- *I* = [0, 1] *Hausdorff* moment problem

The moment problem has a solution on [0, 1] iff sequence  $\{s_n\}_{n\geq 0}$  is completely monotonic, i.e.,

 $(-1)^k (\Delta^k s)_n \geq 0$ 

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- measure with finite support is uniquely determined by its moments (Vandermonde matrix),
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Consequently, we will further discuss the Stieltjes and Hamburger moment problem only.

• For  $\{s_n\}_{n\geq 0}$ , we denote  $H_N(s)$  the  $N \times N$  Hankel matrix with entries  $(H_N(s))_{ij} := s_{i+j}, i, j \in \{0, 1, \dots, N-1\}$ .

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- Define two sesquilinear forms  $H_N$  and  $S_N$  on  $\mathbb{C}^N$  by

$$H_N(x,y) := \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} \overline{x_i} y_j s_{i+j}$$
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- Let  $\mu \in \mathcal{M}_H$  or  $\mu \in \mathcal{M}_S$  with infinite support. By observing that

$$H_N(y,y) = \int \Big| \sum_{i=0}^{N-1} y_i x^i \Big|^2 d\mu(x) \text{ and } S_N(y,y) = \int x \Big| \sum_{i=0}^{N-1} y_i x^i \Big|^2 d\mu(x),$$

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#### Necessary condition for the existence

A necessary condition for the Hamburger moment problem to have a solution (with infinite support) is the sesquilinear form  $H_N$  is PD for all  $N \in \mathbb{Z}_+$ . A necessary condition for the Stieltjes moment problem to have a solution (with infinite support) is both sesquilinear forms  $H_N$  and  $S_N$  are PD for all  $N \in \mathbb{Z}_+$ .

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$$P(x) = \sum_{k=0}^{N-1} a_k x^k$$
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Since

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Since

$$\langle P, A[Q] \rangle = S_N(a, b) = \langle A[P], Q \rangle,$$

A is a symmetric operator.

• Especially,

$$\langle 1, A^n 1 \rangle = s_n, \quad n \in \mathbb{N}.$$

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• Especially, for  $f(x) = x^n$ , one finds

$$s_n = \langle 1, A^n 1 \rangle = \langle 1, (A')^n 1 \rangle = \int_{\mathbb{R}} x^n d\mu(x),$$

since  $Dom(A^n) \subset Dom((A')^n)$ .

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### Existence of the solution

- We see a self-adjoint extension of A yields a solution of the Hamburger moment problem.
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## Theorem (Existence)

i) A necessary and sufficient condition for  $\mathcal{M}_H \neq \emptyset$  (with infinite support) is

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\det H_N(s) > 0 for all N \in \mathbb{N}.
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ii) A necessary and sufficient condition for  $M_S \neq \emptyset$  (with infinite support) is

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• Historically, this result has not been obtained by using the spectral theorem that was invented later.

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- The other direction is even less clear. For not only is it not obvious, it is **false** that every solution of the moment problem arise from some measure given by spectral measure of some self-adjoint extension.
- A solution of the moment problem which comes from a self-adjoint extension of *A* is called *N-extremal* solution (von Neumann [Simon], extremal [Shohat-Tamarkin]).

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- By construction,  $P_n$  is a polynomial of degree n with real coefficients and

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for all  $m, n \in \mathbb{Z}_+$ . These are well-known *Orthogonal Polynomials*.

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•  $\{P_n\}_{n=0}^{\infty}$  are determined by moment sequence  $\{s_n\}_{s=0}^{\infty}$ ,

$$P_n(x) = \frac{1}{\sqrt{\det[H_{n+1}(s)H_n(s)]}} \begin{vmatrix} s_0 & s_1 & \dots & s_n \\ s_1 & s_2 & \dots & s_{n+1} \\ \vdots & \vdots & & \vdots \\ s_{n-1} & s_n & \dots & s_{2n-1} \\ 1 & x & \dots & x^n \end{vmatrix}.$$

• Since span(1, x,...,  $x^n$ ) = span( $P_0, P_1, ..., P_n$ ),  $xP_n(x)$  has an expansion in  $P_0, P_1, ..., P_{n+1}$ .

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 Hence A has, in the basis {P<sub>n</sub>}<sup>∞</sup><sub>n=0</sub>, has tridiagonal matrix representation and Dom(A) is the set of sequences of finite support. • The realization of elements of  $\mathcal{H}^{(s)}$  as  $\sum_{n=0}^{\infty} \lambda_n P_n$ , with  $\sum_{n=0}^{\infty} |\lambda_n|^2 < \infty$  gives a different realization of  $\mathcal{H}^{(s)}$  as a set of sequences  $\lambda = \{\lambda_n\}_{n=0}^{\infty}$  with the usual  $\ell^2(\mathbb{Z}_+)$  inner product.

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$$s_n = (e_0, A^n e_0).$$

Consequently, we reveal following correspondences:

#### Sufficient conditions for determinacy - moment sequence

It is desirable to be able to tell whether the moment problem is determinate (or indeterminate) just by looking at the moment sequence  $\{s_n\}_{n=0}^{\infty}$ , or the Jacobi matrix (seq.  $\{a_n\}_{n=0}^{\infty}$ ,  $\{b_n\}_{n=0}^{\infty}$ ), or orthogonal polynomials  $\{P_n\}_{n=1}^{\infty}$ .

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# Carleman, 1922, 1926

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1) 
$$\sum_{n=1}^{\infty} \frac{1}{\sqrt[2n]{|s_{2n}|}} = \infty$$
 or 2)  $\sum_{n=1}^{\infty} \frac{1}{a_n} = \infty$ 

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• Hence, e.g., if  $\{a_n\}_{n=0}^{\infty}$  is bounded or there are R, C > 0 such that

 $|s_n| \leq CR^n n!,$ 

for all n sufficiently large, we have determinate Hamburger m.p. If

$$|s_n| \leq CR^n(2n)!,$$

for all *n* sufficiently large, we have determinate Stieltjes m.p.

# Chihara, 1989

Let

$$\lim_{n\to\infty} b_n = \infty \quad \text{and} \quad \lim_{n\to\infty} \frac{a_n^2}{b_n b_{n+1}} = L < \frac{1}{4}.$$

then the Hamburger moment problem is determinate if

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• Chihara uses totally different approach to the problem - concept of chain sequences.

• Recall  $\{P_n\}_{n=0}^{\infty}$  are determined by the three-term recurrence

$$xP_n(x) = a_nP_{n+1}(x) + b_nP_n(x) + a_{n-1}P_{n-1}(x)$$

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• Let us denote by  $\{Q_n\}_{n=0}^{\infty}$  a polynomial sequence that solve the same recurrence as  $\{P_n\}_{n=0}^{\infty}$  with initial conditions  $Q_0(x) = 0$  and  $Q_1(x) = \frac{1}{b_0}$ .

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The Hamburger moment problem is determinate if and only if

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- It is even necessary and sufficient that there exists a z ∈ C \ ℝ such that both {P<sub>n</sub>(z)}<sup>∞</sup><sub>n=0</sub> and {Q<sub>n</sub>(z)}<sup>∞</sup><sub>n=0</sub> does not belong to ℓ<sup>2</sup>(ℤ<sub>+</sub>).

# Sufficient conditions for indeterminacy - density of measure

 Sometimes the natural starting point is not orthogonal polynomials of Jacobi matrix but a density w with moments {s<sub>n</sub>}<sup>∞</sup><sub>n=0</sub>.  Sometimes the natural starting point is not orthogonal polynomials of Jacobi matrix but a density w with moments {s<sub>n</sub>}<sup>∞</sup><sub>n=0</sub>.

### Krein, 1945

Let w be a density of  $\mu$  (i.e.,  $d\mu(x) = w(x)dx$ ) where either 1) supp(w) =  $\mathbb{R}$  and

$$\int_{\mathbb{R}}\frac{\ln(w(x))}{1+x^2}dx>-\infty,$$

or 2)  $\operatorname{supp}(w) = [0, \infty)$  and

$$\int_0^\infty \frac{\ln(w(x))}{\sqrt{x}(1+x)} dx > -\infty.$$

Suppose that for all  $n \in \mathbb{Z}_+$ :

$$\int_{\mathbb{R}}|x|^{n}w(x)dx<\infty.$$

Then the moment problem (Hamburger in case (1), Stieltjes in case(2)) with moments

$$s_n = \frac{\int x^n w(x) dx}{\int w(x) dx}$$

is indeterminate.

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## Nevanlinna, 1922

The solutions of the Hamburger moment problem in the indeterminate case are parametrized via homeomorphism  $\phi \mapsto \mu_{\phi}$  of  $\mathcal{P} \cup \{\infty\}$  onto  $\mathcal{M}_H$  given by

$$\int_{\mathbb{R}} \frac{d\mu_{\phi}(x)}{x-z} = -\frac{A(z)\phi(z) - C(z)}{B(z)\phi(z) - D(z)}, \quad z \in \mathbb{C} \setminus \mathbb{R},$$

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- A, B, C, D are called Nevanlinna functions and  $\begin{pmatrix} A & C \\ B & D \end{pmatrix}$  the Nevanlinna matrix.
- The solution  $\mu_\phi$  can be then expressed by using Stiltjes-Perron inversion formula.

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- Extreme points are dense in  $\mathcal{M}_H$ .

# **Example due to Stieltjes**

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Moreover, denoting

$$d\mu_{\vartheta}(u) = \frac{1}{\sqrt{\pi}} u^{-\ln u} \left[1 + \vartheta \sin(2\pi \ln u)\right] du,$$

then, for  $\vartheta \in (-1, 1)$ , function

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 Hence polynomials are not dense in L<sup>2</sup>(dμ<sub>ψ</sub>). This is a typical situation for solutions of indeterminate moment problems which are not N-extremal. • In some sense, to solve indeterminate Hamburger moment problem means to find the Nevanlinna functions *A*,*B*,*C*, and *D* (in particular *B* and *D*).

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$$\begin{aligned} A(z) &= z \sum_{k=0}^{\infty} Q_k(0) Q_k(z), \qquad C(z) = 1 + z \sum_{k=0}^{\infty} P_k(0) Q_k(z) \\ B(z) &= -1 + z \sum_{k=0}^{\infty} Q_k(0) P_k(z), \qquad D(z) = z \sum_{k=0}^{\infty} P_k(0) P_k(z), \end{aligned}$$

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More on A,B,C,D:

- A,B,C,D are entire functions of order  $\leq 1$ , if the order is 1, the exponential type is 0 [Riesz, 1923]
- *A*,*B*,*C*,*D* have the same order, type and Phragmén-Lindenlöf indicator function [Berg and Pedersen, 1994]

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- They are the only solutions for which polynomials C[x] are dense in L<sup>2</sup>(ℝ, μ<sub>t</sub>) ({P<sub>n</sub>} forms an orthonormal basis of L<sup>2</sup>(ℝ, μ<sub>t</sub>)), [Riesz, 1923].

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- N-extremal solutions are indeed extreme points in  $\mathcal{M}_H$  but not the only ones.

If we set

$$\phi(z) = egin{cases} eta+i\gamma, & \Im z>0, \ eta-i\gamma, & \Im z<0, \end{cases}$$

for  $\beta \in \mathbb{R}$  and  $\gamma > 0$ , then  $\phi \in \mathcal{P}$  and  $\mu_{\beta,\gamma}$  is absolutely continuous with density

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- Polynomials  $\mathbb{C}[x]$  are not dense in  $L^1(\mathbb{R}, \mu_{\beta,\gamma})$ .
- The solution μ<sub>0,1</sub> is the one that maximizes certain entropy integral, see Krein's condition. More general and additional information are provided in [Gabardo, 1992].

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- The only N-extremal solutions supported within  $[0, \infty)$  are  $\mu_t$  with  $\alpha \le t \le 0$ .
- For the indeterminate Stieljes moment problem there is a sligtly more elegant way how to describe  $\mathcal{M}_S$  known as *Krein parametrization*, [Krein, 1967].



Thank you, and see you in Beskydy!